

Linear Mixed Models - A Short Review

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Mixed Models in a Nutshell: Theory and Concepts

Mixed linear models are a particular class of models containing both fixed and random effects. Loosely speaking, a mixed model is a model where some terms remain constant over repeated sampling and some other terms vary at random according to some distribution. For simplicity from now on we will drop the notation linear and refer to these models simply as mixed models. For any mixed model we can identify three main components: the equation of the model, the expectations and Variance-Covariance for the random effects, and all the remaining assumptions regarding the model.

The model

A model is a mathematical representation of our understanding of the biological process that explains our observations. We can think of each observation as a single equation (and in this case we are confining ourselves to linear equations), containing the trait of interest, and the factors that explain the observations. For example:

 $a_1x_1 + a_2x_2 + ... + a_nx_n = b$

A system of equations is then a set of these single linear equations and a solution for the system must satisfy all equations. With *n* unknown the system takes form:

 $a_{11}x_1 + a_{12}x_2 + ... + a_{1n}x_n = b_1$ $a_{21}x_1 + a_{22}x_2 + ... + a_{2n}x_n = b_2$ $a_{31}x_1 + a_{32}x_2 + ... + a_{3n}x_n = b_3$ $\ddot{\cdot}$ $a_{m1}x_1 + a_{m2}x_2 + \ldots + a_{mn}x_n = b_m$

The model

The same set of equation can be rewritten in a more convenient matrix notation

 $Ax = b$

where

$$
\mathbf{A} = \begin{bmatrix} a_{11} + a_{12} + \dots + a_{1n} \\ a_{21} + a_{22} + \dots + a_{2n} \\ a_{31} + a_{32} + \dots + a_{3n} \\ \vdots \\ a_{m1} + a_{m2} + \dots + a_{mn} \end{bmatrix}, \quad \mathbf{x} = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ \vdots \\ x_n \end{bmatrix}, \quad \mathbf{b} = \begin{bmatrix} b_1 \\ b_2 \\ b_3 \\ \vdots \\ b_n \end{bmatrix}
$$

The model

From now on we will assume that our model contain both fixed and random effects (more on it below). Traditionally mixed models have been represented in matrix form as follow

where

y is the vector of the observations (observables),

b is a vector of fixed effects

u is a vector of random effects (unknown),

e is a vector of residual (whatever we cannot explain with our model) which are also random, **X** and **Z** are incidence matrices, assigning each element of **b** and **u** to their corresponding element in **y**.

Fixed and random effects

The distinction between fixed and random applies to the unknown model components.

> A fixed effect is a known constant that will remain the same over conceptual repeated sampling

A random effect is a random variable that arises from the subsampling and random selection of "treatment" levels.

In reality the distinction between fixed and random effects often depends on the practical use and interpretation of parameter estimates. When the investigator is interested in comparing specific levels of a certain factors (let's say amount of fertilizer for a plant or concentrate for a cow) than it is sensible to consider them as fixed effect. When a parameter is not of relevance for the analysis but rather a nuisance that we want to account for, more often than not we end up treating that effect as random. Also keep in mind that one of the advantages of random effects is their parsimony.

Expectations and variance-covariance for the random effects

Since we have assumed that random effects come from some large population we need to define location and dispersion for these parameters. Note that we have assumed that our observations are normally distributed and we will always assume that our residuals are normally distributed. Keeping the general matrix notation that we have seen before the expectations of, **u e** and **y** are

 $E(\mathbf{u}) = \mathbf{0}$

 $E(\mathbf{e}) = \mathbf{0}$

 $E(y) = E(Xb + Zu + e)$

- $= E(\mathbf{X}\mathbf{b}) + E(\mathbf{Z}\mathbf{u}) + E(\mathbf{e})$
- $= XE(\mathbf{b}) + ZE(\mathbf{u}) + E(\mathbf{e}),$
- $=\mathbf{X}\mathbf{b}+\mathbf{0}+\mathbf{0}$
- $= X_b$

Expectations and variance-covariance for the random effects

Also, the variances of **u** and **e** are

$$
\mathbf{V} = \left(\begin{array}{c} \mathbf{u} \\ \mathbf{e} \end{array}\right) = \left(\begin{array}{cc} \mathbf{G} & \mathbf{0} \\ \mathbf{0} & \mathbf{R} \end{array}\right)
$$

The actual structure of **G** and **R** is flexible we will discuss this in later lectures but in the simplest cases

 $G=I\sigma_u^2$ and $R=I\sigma_e^2$

Expectations and variance-covariance for the random effects

```
cov(\mathbf{u}, \mathbf{e}) = 0, so that
V(y) = V(Xb + Zu + e)=V(Zu+e)= ZV(u)Z' + V(e) + ZCov(u,e) + Cov(e,u)Z'= ZGZ' + RCov(y, u) = ZGCov(y, e) = RIf we call
```
 $V = ZGZ' + R$

A trivial example – Daughters Lactation Yield

 $110 = herd_1 + site_{ZA} + e$ $100 = herd_1 + sire_{AD} + e$ $110 = herd₂ + site_{BB} + e$ $100 = herd_2 + sire_{DD} + e$ $100 = herd₂ + site_{DD} + e$ $110 = herd_3 + sire_{CC} + e$ $110 = herd_3 + sire_{CC} + e$ $100 = herd_3 + sire_{AD} + e$ $100 = herd_3 + site_{AD} + e$

18 V=Z%*%(G)%*%t(Z)+(R)

A trivial example – Daughters Lactation Yield

Solving the model

consider *variance components as a fixed quantity estimated a priori*.

$\hat{\mathbf{u}} = \mathbf{GZ'V}^{-1}(\mathbf{y} - \mathbf{X})$ ˆ **b)**

 $\mathbf{b} = (\mathbf{X}'\mathbf{V}^{-1}\mathbf{X})^{-1}\mathbf{X}'\mathbf{V}^{-1}\mathbf{y}$

 $\hat{\mathbf{b}}$ = (105.64,104.28,105.46)' $\hat{\mathbf{u}}$ = (0.40,0.52,0.76,-1.67)'

The mixed model equations

For the general mixed linear model described above, a particular set of equation can be used in finding the solutions of each effect. These are the Henderson's mixed model equations and were developed for animal breeding by C.R. Henderson (Henderson, 1949).

$$
\begin{bmatrix}\nX'R^{-1}X & Z'R^{-1}X \\
X'R^{-1}Z & Z'R^{-1}Z + G^{-1}\n\end{bmatrix}\n\begin{bmatrix}\n\hat{\mathbf{b}} \\
\hat{\mathbf{u}}\n\end{bmatrix} =\n\begin{bmatrix}\nX'R^{-1}y \\
Z'R^{-1}y\n\end{bmatrix}
$$
\nWe usually call this the Left Hand Side (L)

We usually call this the Right

Hand Side (RHS)

The mixed model equations

If we assume that residual variance is IID (identical and independent for all observations), the R matrix can be factored out. In most of the applications we will see from now on the following form of the equations will be more convenient and therefore used:

$$
\begin{bmatrix}\n\mathbf{X}'\mathbf{X} & \mathbf{Z}'\mathbf{X} \\
\mathbf{X}'\mathbf{Z} & \mathbf{Z}'\mathbf{Z} + \mathbf{I}\alpha\n\end{bmatrix}\n\begin{bmatrix}\n\hat{\mathbf{b}} \\
\hat{\mathbf{u}}\n\end{bmatrix} = \begin{bmatrix}\n\mathbf{X}'\mathbf{y} \\
\mathbf{Z}'\mathbf{y}\n\end{bmatrix}
$$
\n
$$
\begin{bmatrix}\n\text{X}'\mathbf{x} & \text{X}'\mathbf{Z}\n\end{bmatrix}^{-1}\n\begin{bmatrix}\n\text{X}'\mathbf{y} \\
\text{Z}'\mathbf{y}\n\end{bmatrix} \leftarrow \text{BLUE fixed effects}
$$
\n
$$
\begin{bmatrix}\n\text{Z}'\mathbf{x} & \text{Z}'\mathbf{Z} + \text{I}\alpha\n\end{bmatrix}^{-1}\n\begin{bmatrix}\n\text{X}'\mathbf{y} \\
\text{Z}'\mathbf{y}\n\end{bmatrix} \leftarrow \text{BLUP random effects}
$$

The mixed model equations

BLUE and BLUP

While we will not embark in a description of the statistical properties of BLUP and BLUE a reminder of why we like them so much is in order.

They maximize correlations between true values and predicted values (they are BEST) among the (LINEAR) functions of the observations.

The estimates of the fixed effects are (UNBIASED) and the mean of the true (unknown) random effects is equal to the mean of the predicted random effects.

Estimability in models with multiple fixed effects

When there are multiple effects in the model it is often impossible to obtain unique BLUE for each level of the fixed effects.

X'X is not full rank since its dimension is 7x7 yet there are only 6 independent rows and columns. In this case a unique inverse of the coefficient matrix (**X'X**) does not exist. Therefore we cannot obtain the BLUE estimates for herd and sire.

Linear functions of the solutions are still estimable.

sire<-c("ZA","AD","BB","AD","AD","CC","CC","AD","AD") #sires herd<-c("one","one","two","two","two","three","three","three","three") #herds yield<-c(110,100,110,100,100,110,110,100,100) #yields new data<-as.data.frame(cbind(yield,herd,sire)) # putting everything in a dataframe new data\$yield<-as.numeric(as.character(new data\$yield)) # yield as numeric fm<-lm(yield~ herd + sire -1,data=new data) # omitting the intercept (-1)

case). Model was reparametrized to be full rank the solutions presented are estimable function of the (unknown) BLUEs

*Sire*_{AD} − *Sire_{CC}* $Sire_{AD} - Sire_{ZA}$

Standard errors and accuracy of the estimates

Accuracy refers to the correlation between true and predicted random effects. Calculation of these values requires knowledge of the inverse elements of the mixed model equations.

$$
\left[\begin{array}{cc} \mathbf{X}'\mathbf{X} & \mathbf{Z}'\mathbf{Z} \\ \mathbf{Z}'\mathbf{X} & \mathbf{Z}'\mathbf{Z}+\mathbf{I}\alpha \end{array}\right] = \left[\begin{array}{cc} \mathbf{C}_{11} & \mathbf{C}_{12} \\ \mathbf{C}_{21} & \mathbf{C}_{22} \end{array}\right]
$$

$$
\begin{bmatrix} \mathbf{C}_{11} & \mathbf{C}_{12} \\ \mathbf{C}_{21} & \mathbf{C}_{22} \end{bmatrix}^{-1} = \begin{bmatrix} \mathbf{C}^{11} & \mathbf{C}^{12} \\ \mathbf{C}^{21} & \mathbf{C}^{22} \end{bmatrix}
$$

$$
PEV = V(\hat{\mathbf{u}} - \mathbf{u}) = \mathbf{C}^{22} \sigma_e^2
$$

$$
PEV_i = (d_i \sigma_e^2)
$$
Diagonal element of C²²

Standard errors and accuracy of the estimates

As an aside, the sum of each row in C22 is equal to the variance of true sire effect values, which in this case we defined as 0.1 (rounding error causes these example values to be a little bit off):

 PEV_i)/V(t<u>ruevalues). UP SEP REL</u> Another measure of the accuracy of the BLUPs is reliability, defined as the squared correlation between predicted and true values (reliability ranges from 0 to 1). For each BLUP *i*, we can compute reliability as (V(true values) –

Mixed models compared to traditional ANOVA

In this section, we focus on hypothesis testing and estimation of an empirical data set to show how these analyses are conducted for different methods and for different software packages. Only a few details of the mathematical machinery involved in the mixed models analysis will be covered here.

A more detailed description of mixed model theory will be covered in later sections of the book. For readers interested in a more formal treatment of the argument details, they can be found in Sorensen and Gianola (3). Details of ANOVA for balanced and unbalanced data can be found in Rawlings et al. (2001) and Milliken and Johnson (2004).

Mixed models compared to traditional ANOVA

Example data (MaizeRILs.csv) were obtained by testing 62 recombinant inbred line (RIL) progeny from the cross between inbred maize lines B73 and Mo17.

RILs were grown in experimental units (plots) of 20 plants each using a randomized complete block design with two replications at each of four locations.

Five plants in each plot were measured for height.

The mean height for each plot is the independent variable used for this experiment.

Some data were missing from the actual data set, these were filled in with simulated data to create a balanced data set for demonstration.

Mixed models compared to traditional ANOVA

The linear model for this experiment is:

Y_{ijk} = μ + L_i + $B(L)_{ij}$ + G_k + GL_{ik} + ε_{ijk} ,

Where

 μ = overall mean,

 L_i = effect of location *i*,

 $B(L)_{ii}$ = effect of block *j* nested within location *i* (replication effect),

 G_k = effect of genotype k (RIL effect),

GLik = effect of interaction between genotype *k* and location *i*,

 ε_{ijk} = residual (experimental error) effect of the plot containing genotype *k* in block *j* of location *i*.

We will assume that all effects except the overall mean are random

ANOVA SAS GLM

```
proc glm data = ril.maizeril; 
class location rep RIL; 
model height = location rep(location) RIL RIL*location; 
random location rep(location) RIL RIL*location/test; 
lsmeans RIL; 
run;
```
Default F-tests for each factor shown here are correct only for the model in which all effects except residuals are fixed.

Default F-tests use the residual error variance as the denominator in all cases.

Since we have assumed that all effects are random, the correct form of the F-test depends on the expected mean squares.

*F = MS(RIL)/MS(location*RIL) = 2539.959/114.7508 = 22.13 with 61 and 183 df.*

proc glm;

class location rep RIL; model mean_height = location rep(location) RIL RIL*location; random location rep(location) RIL RIL*location/test; lsmeans RIL;

run;

*F = MS(RIL)/MS(location*RIL) = 2539.959/114.7508 = 22.13 with 61 and 183 df.*

ANOVA SAS GLM

 $\hat{\sigma}_{\varepsilon}^2 = MS(error) = 64.89$

$$
\hat{\sigma}_{GL}^2 = \frac{MS(location * RIL) - MS(error)}{n_b} = \frac{114.75 - 64.89}{2} = 24.93
$$

$$
\hat{\sigma}_G^2 = \frac{MS(RIL) - MS(location * RIL)}{n_b} = \frac{2539.96 - 114.75}{0} = 303.15
$$

 $n_l n_b$

8

Var Comp. method of moments \rightarrow equate the observed mean squares to their expectations and solve for the variance components

Predicted marginal mean value of each RIL using the "lsmeans"

ANOVA R

```
#ANOVA
m0 <- lm(mean height~location*RIL + rep:location)
anova(model)
# Polulation means ( LSMEANS )
pma <- popMatrix(mm, effect='RIL') # obtaining L
RILMeans <- popMeans(model, effect='RIL')
```


Balanced data – mixed models analysis with SAS Proc MIXED

proc mixed covtest; class location rep RIL; model mean height = /solution; random location rep(location) RIL RIL*location/solution; ods output solutionR = random solutionF = fixed;

- No degrees of freedom, sum of squares squares, or F-tests for random term
- VarComp estimated
- REML varcomp=Moment method balanced design

Balanced data – mixed models analysis with R

```
require(1me4, quite=T)mm <-1mer(mean height \sim 1 + (1|RIL) + (1|location/rep) +
(1 | location: RIL))print(mm)
```

```
Linear mixed model fit by REML
Formula: mean height \sim 1 + (1 | RIL) + (1 | location/rep) + (1
location:RIL)
  Data: rils
 AIC BIC logLik deviance REMLdev
 3845 3870 -1917
                    3839
                            3833
Random effects:
                    Variance Std.Dev.
Groups
             Name
location: RIL (Intercept) 24.932 4.9932
RIL
     (Intercept) 303.151 17.4112
rep: location (Intercept) 13.446 3.6669
location (Intercept) 220.661 14.8547
Residual
                         64.886 8.0552
Number of obs: 496, groups: location:RIL, 248; RIL, 62;
rep: location, 8; location, 4
Fixed effects:
           Estimate Std. Error t value
(Intercept) 182.119
                        7.869
                                23.14
```
Hypothesis testing with mixed models

Hypothesis testing for the variance components can be based on the "Z value" obtained by using the "covtest" option in the Proc MIXED statement.

The Z value is the ratio of the variance component to its standard error, which has a Z distribution. This test has low power, particularly for variance components estimated with few degrees of freedom.

Hypothesis testing with higher power can be implemented with the likelihood ratio test.

This test requires one to perform an additional Proc MIXED analysis for each factor to be tested, in which one removes the factor of interest from the model.

The likelihood of this "reduced" model can be compared to the likelihood of the "full" model to form a test of the null hypothesis that the variance component for the dropped term is zero.

If removing the term causes a large decrease in the likelihood of the model, then there is more evidence that the variance component for the term is greater than zero.

Test significance of location main effect by dropping it from model, compute likelihood of reduced model:

proc mixed;

```
class rep RIL;
model mean height =;
random rep(location) RIL RIL*location;
```
Fit Statistics -2 Res Log Likelihood 3841.3

LRT = (-2) ln (likelihood of reduced model / likelihood of full model) $= -2 * ln (likelihood of reduced model) - (-2) * ln (likelihood of full)$ model) $= 3841.3 - 3833.2 = 8.1$

LRT has approx. chi-square distribution. DF equal the number of parameters (variance components) that differ between the models. The raw *p*-value should be divided by 2. H₀: σ^2 _{location} = 0, raw *p*-value of χ^2 with value 8.1 and df of 1 = 0.004. Adjusted *p*-value = 0.002

Prediction of random factors with mixed models

To compare the estimation of RIL values from Proc MIXED and Proc GLM, the first difference one will notice is that an error message will result if one includes the statement "lsmeans RIL" as part of the Proc MIXED analysis.

In practice, we obtain the RIL effect predictions by requesting the solutions for the random effects in the model using the "/solution" option on the random statement in Proc MIXED.

We can then construct best linear unbiased predictors (BLUP) in this case by simply adding the estimated overall mean effect (μ, obtained with the "/solution" option on the model statement) to each RIL effect prediction

The GLM Procedure Dependent Variable: mean_height

- First, notice that the degrees of freedom for RIL are still 61 but the degrees of freedom for location*RIL are now 180 instead of 183.
- The reason for this is that we have no data on two of the location*RIL interactions involving RIL-5 (because we have no data on this RIL from two locations) and one of the location*RIL interactions involving RIL-51 (as it is missing in one location).
- Second, note that now the Type I and Type III sums of squares (SS) and mean square (MS) results are different from each other in this case. This occurs because the
	- Type I statistics are computed by fitting the effects in the order given in the model and computing the sums of squares accounting for each term sequentially, whereas the
	- Type III statistics are computed by calculating the sums of squares attributable to each term after accounting for all other terms in the model.
- In the case of balanced data, all of the model terms are orthogonal to each other such that the order of fitting factors affects how much variation they are associated with.
- In contrast, with unbalanced data, the different factors can become correlated and the variation associated with any one term may also be partly associated with a different term, such that the order of fitting terms affects the sums of squares for the term.
- Because of this, Type III statistics are preferred since they indicate the amount of variation attributable to each factor after accounting for the other factors in the model

As a result, the sum of Type III statistics will be less than the total sums of squares for the model: in this example the sum of the Type III SS = 248784.7251, whereas the total SS for the model is 266774.8025.

- Variance components can be estimated by the method of moments from ANOVA Type III MS, but two complications arise in the case of unbalanced data:
	- First, such estimates are reasonable estimates if the data are not too badly balanced, but the statistical properties of such estimators are unknown, so it can be difficult to know how reliable they are for a given data set.
	- Second, the expected mean squares shown for the balanced data set above are not correct for the unbalanced data case, as the coefficients on the variance components are affected by the data structure.
	- The computation of the coefficients can be horribly complex (see Rawlings and Messy Data books), but we can get the coefficients using SAS Proc GLM with the random statement, resulting in this output:

$$
F_{RIL} = \frac{MS(RIL)}{MS(location * RIL)} = \frac{\sigma_{\varepsilon}^2 + 2\sigma_{location * RIL}^2 + 8\sigma_{RIL}^2}{\sigma_{\varepsilon}^2 + 2\sigma_{location * RIL}^2} = 1 + \frac{8\sigma_{RIL}^2}{\sigma_{\varepsilon}^2 + 2\sigma_{location * RIL}^2}
$$

WITH BALANCE

$$
F_{RIL} = \frac{MS(RIL)}{MS(location * RIL)} = \frac{\sigma_{\varepsilon}^2 + 1.9149 \sigma_{location * RIL}^2 + 7.6105 \sigma_{RIL}^2}{\sigma_{\varepsilon}^2 + 1.9348 \sigma_{location * RIL}^2}
$$

WITH NO BALANCE

As this expectation does not equal 1 when the null hypothesis is true (RIL variance component = 0), the Ftest is not correct. Instead, more complicated forms of the F-test are required, and Proc GLM computes these forms when the random statement is given:

The GLM Procedure Tests of Hypotheses for Random Model Analysis of Variance Dependent Variable: mean_height

Source **DF** Type III SS Mean Square F Value Pr > F location 3 77172 25724 27.00 0.0031 Error 4.2929 4089.266951 952.566239 Error: 0.9999*MS(rep(location)) + 0.9701*MS(location*RIL) - 0.9699*MS(Error)

$$
\hat{\sigma}_{\varepsilon}^2 = MS(error) = 67.37
$$

$$
\hat{\sigma}_{GL}^2 = \frac{MS(location * RIL) - MS(error)}{1.9348} = \frac{101.61 - 67.37}{1.9348} = 17.7
$$

$$
\hat{\sigma}_G^2 = \frac{MS(RIL) - MS(location * RIL)}{8} = \frac{2539.96 - 114.75}{8} = 303.15
$$

LSmeans

$$
(\mathbf{Y}_{\ldots k}) = \mu + \bar{L}_{\ldots} + \overline{B(L)}_{\ldots} + G_k + \overline{GL}_{\ldots k}
$$

In the fixed model, the interaction of a genotype-by-location interaction effect is non-estimable if there are no data on that combination of genotype and location. Then if some interaction effects included in the LSmean equation are non-estimable, the whole LSmean is non-estimable

Unbalanced data – mixed models analysis

Same model with proc mixed

LSmean (BLUE):

BLUP:
$$
\hat{Y}_{.k} = \mu + G_k
$$